

2012 Mathematics

Advanced Higher

Finalised Marking Instructions

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Marks awarded for

1. (3,4)	(a) $f(x) = \frac{3x + 1}{x^2 + 1}$ $f'(x) = \frac{3(x^2 + 1) - (3x + 1)2x}{(x^2 + 1)^2}$ $= \frac{3x^2 + 3 - 6x^2 - 2x}{(x^2 + 1)^2}$ $-3x^2 - 2x + 3$	1M 1 1	for quotient rule (or product) for two correct terms for third correct term
	$= \frac{-3x^2 - 2x + 3}{(x^2 + 1)^2}$ (b) $g(x) = \cos^2 x e^{\tan x}$ $g'(x) = 2\cos x (-\sin x) e^{\tan x} + (\cos^2 x) (\sec^2 x) e^{\tan x}$ $= -\sin 2x e^{\tan x} + e^{\tan x}$ $= (1 - \sin 2x) e^{\tan x}$	1M 1 1 1	product rule first correct term second correct term simplification
	(b) alternative $g(x) = \cos^{2} x \exp(\tan x)$ $\ln(g(x)) = \ln(\cos^{2} x) + \tan x$ $= 2 \ln(\cos x) + \tan x$ Differentiating $\frac{g'(x)}{g(x)} = 2\frac{(-\sin x)}{\cos x} + \sec^{2} x$ $g'(x) = \left(\frac{1-2\sin x \cos x}{\cos^{2} x}\right) \cos^{2} x \exp(\tan x)$	1M 1 1	
2. (5)	$= (1 - \sin 2x) \tan x$ $a = 2048 \text{ and } ar^{3} = 256$ $\Rightarrow r^{3} = \frac{1}{8}$ $\Rightarrow r = \frac{1}{2}.$ $S_{n} = \frac{a(1 - r^{n})}{1 - r}$ $\Rightarrow \frac{1 - (\frac{1}{2})^{n}}{1 - \frac{1}{2}} = \frac{4088}{2048}$ $= \frac{511}{256}$	1	valid approach correct answer only, 2 marks for sum formula
	$\Rightarrow 1 - \left(\frac{1}{2}\right)^{n} = \frac{511}{256} \times \frac{1}{2} = \frac{511}{512}$ $\frac{1}{2^{n}} = 1 - \frac{511}{512} = \frac{1}{512}$ $\Rightarrow 2^{n} = 512 \Rightarrow n = 9$	1 1	any valid method

3. (6)	Since w is a root, $\overline{w} = -1 - 2i$ is also a root. The corresponding factors are (z + 1 - 2i) and $(z + 1 + 2i)from which((z + 1) - 2i)((z + 1) + 2i) = (z + 1)^2 + 4= z^2 + 2z + 5z^3 + 5z^2 + 11z + 15 = (z^2 + 2z + 5)(z + 3)The roots are (-1 + 2i), (-1 - 2i) and -3.$	1 1 1 1 1	for conjugate evidence needed for stating roots together for two correct points for third correct point
4. (5)	The general term is given by: $\binom{9}{r}(2x)^{9-r}\left(-\frac{1}{x^2}\right)^r$ $= \binom{9}{r} \times \frac{2^{9-r}x^{9-r}(-1)^r}{x^{2r}}$ $= \binom{9}{r} \times (-1)^r 2^{9-r}x^{9-3r}$	1 1 1	

$-\binom{r}{r} \wedge \binom{-1}{2} \frac{r}{2}$	1	
The term independent of x occurs when		
9 - 3r = 0, i.e. when $r = 3$.	1	
The term is: $\frac{9!}{6! 3!} (-1)^3 2^6$		
= -5376.	1	

5. (5)	Method 1 $\overrightarrow{PQ} = 3\mathbf{i} + \mathbf{j} + 4\mathbf{k}$ and $\overrightarrow{QR} = 2\mathbf{i} - 2\mathbf{j} - 2\mathbf{k}$	1	\overrightarrow{PR} could be used
	A normal to the plane: $\overrightarrow{PQ} \times \overrightarrow{QR} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 3 & 1 & 4 \\ 2 & -2 & -2 \end{vmatrix}$	1M	
	$= \mathbf{i} \begin{vmatrix} 1 & 4 \\ -2 & -2 \end{vmatrix} - \mathbf{j} \begin{vmatrix} 3 & 4 \\ 2 & -2 \end{vmatrix} + \mathbf{k} \begin{vmatrix} 3 & 1 \\ 2 & -2 \end{vmatrix}$		
	$= 6\mathbf{i} + 14\mathbf{j} - 8\mathbf{k}$	1	
	Hence the equation has the form: 6x + 14y - 8z = d.	1	
	The plane passes through $P(-2, 1, -1)$ so d = -12 + 14 + 8 = 10		
	which gives an equation $6x + 14y - 8z = 10$	1	
	i.e. $3x + 7y - 4z = 5$.		

Method 2 A plane has an equation of the form ax + by + cz = d. Using the points P, Q, R we get -2a + b - c = da + 2b + 3c = d**1M** 3a + c = dUsing Gaussian elimination to solve these we have or other valid method $\begin{vmatrix} -2 & 1 & -1 & d \\ 1 & 2 & 3 & d \\ 3 & 0 & 1 & d \end{vmatrix}$ $\Rightarrow \begin{array}{|c|c|c|c|c|} -2 & 1 & -1 & d \\ 0 & 5 & 5 & 3d \\ 0 & 6 & 8 & 2d \end{array}$ 1 $\Rightarrow \quad \begin{vmatrix} -2 & 1 & -1 & d \\ 0 & 5 & 5 & 3d \\ 0 & 0 & 2 & -\frac{8}{5}d \end{vmatrix}$ 1 $\Rightarrow c = -\frac{4}{5}d, \qquad b = \frac{7}{5}d, \qquad a = \frac{3}{5}d$ 1 These give the equation $(\frac{3}{5}d)x + (\frac{7}{5}d)y + (-\frac{4}{5}d)z = d$ i.e. 3x + 7y - 4z = 51





8.	$x = 4\sin\theta \implies dx = 4\cos\theta d\theta$	1	
(6)	$ \begin{array}{cccc} x &= & 0 \implies \theta &= & 0 \\ x &= & 2 \implies \theta &= & \frac{\pi}{6} \end{array} $	1	
	$\int_{0}^{2} \sqrt{16 - x^{2}} dx$		
	$= \int_0^{\pi/6} \sqrt{16 - (4\sin\theta)^2} \cdot 4\cos\theta d\theta$	1	
	$= \int_0^{\pi/6} \sqrt{16(1-\sin^2\theta)} \cdot 4\cos\theta \ d\theta$		
	$= \int_0^{\pi/6} \sqrt{16 \cos^2 \theta} \cdot 4 \cos \theta d\theta$		
	$= \int_0^{\pi/6} 16 \cos^2\theta d\theta$	1	
	$= 8 \int_0^{\pi/6} (1 + \cos 2\theta) d\theta$		
	$= 8 \left[\theta + \frac{1}{2}\sin 2\theta\right]_0^{\pi/6}$	1	for applying trig. identity and integrating
	$=\frac{8\pi}{6}+4\sin\frac{\pi}{3}$		
	$= \frac{4\pi}{3} + 2\sqrt{3} \left(\approx 7.65\right)$	1	numerical approx. allowed
9.	Method 1		1
9. (4)	$A + A^{-1} = I$		
	$A^2 + I = A$	1	for multiplying by A
	Hence $A^2 + I = I - A^{-1}$	1	for rearranging $A + A^{-1} = I$
	$A^2 = -A^{-1}$	1	for subtracting I
	$A^3 = -I$, i.e. $k = -1$	1	for multiplying by A
	Method 2		
	$A + A^{-1} = I$		
	$A = I - A^{-1}$	1	for rearranging
	$A^2 = I - 2A^{-1} + (A^{-1})^2$	1	for squaring
	$A^3 = A - 2I + A^{-1}$	1	for multiplying by A
	$A^{3} = (A + A^{-1}) - 2I = I - 2I$		
	Hence $A^3 = -I$, i.e. $k = -1$	1	
	Method 3		
	$A + A^{-1} = I$		
	$A = I - A^{-1}$	1	for rearranging
	$A^3 = A^2 - A$	1	for multiplying by A^2
	$A^3 = (A - I) - A$	1	using $A^2 = A - I$
	= -I, i.e. $k = -1$	1	
	Plus other valid methods.		<u> </u>

Method 1 10. (3) $1234 = 7 \times 176 + 2$ 1 $176 = 7 \times 25 + 1$ $25 = 7 \times 3 + 4$ 1 Hence $1234_{10} = 3412_7$ answer only, 1 of 3 1 Method 2 $1234 = 7 \times 176 + 2$ 1 $= 7 \times (7 \times 25 + 1) + 2$ $= 7 \times (7 \times (7 \times 3 + 4) + 1) + 2$ 1 $= 3 \times 7^{3} + 4 \times 7^{2} + 1 \times 7 + 2$ Hence $1234_{10} = 3412_7$ 1 answer only, 1 of 3 11. $\frac{d}{dr}(\sin^{-1}x) = \frac{1}{\sqrt{1-r^2}}$ (a) 1 (1,4)(b) $\int \sin^{-1} x \cdot \frac{x}{\sqrt{1-x^2}} dx =$ $\sin^{-1}x\int_{\sqrt{1-x^2}}^{x} dx - \int \left(\frac{d}{dx}(\sin^{-1}x)\int_{\sqrt{1-x^2}}^{x} dx\right) dx$ 1 $=\sin^{-1}x\int_{\sqrt{1-x^2}}^{x} dx - \int_{\sqrt{1-x^2}}^{1}\int_{\sqrt{1-x^2}}^{x} dx dx$ $=\sin^{-1}x(-\sqrt{1-x^2})-\int(\frac{1}{\sqrt{1-x^2}}(-\sqrt{1-x^2}))dx$ 1 for $\int \frac{x}{\sqrt{1-x^2}} dx = -\sqrt{1-x^2}$ $= \sin^{-1} x \left(-\sqrt{1 - x^2} \right) - \int (-1) dx$ 1 $= x - \sin^{-1} x \sqrt{1 - x^2} + c$ 1 12. $\frac{dr}{dt} = -0.02; \qquad \frac{dh}{dt} = 0.01$ 1 (5) $V = \pi r^2 h$ for implicit differentiation $\frac{dV}{dt} = \pi \left(2r \frac{dr}{dt} \right) h + \pi r^2 \frac{dh}{dt}$ **1M** for accuracy 1 $= \pi \left(2 \times 0.6 \times (-0.02) \times 2 + 0.36 \times 0.01 \right)$ 1 $= \pi (-0.048 + 0.0036)$ $= -0.0444\pi (\approx -0.14)$ The rate of change in the volume is -0.0444π m³ s⁻¹. 1 units required

13. (10)	$x = 2t + \frac{1}{2}t^{2} \implies \frac{dx}{dt} = 2 + t$ $y = \frac{1}{3}t^{3} - 3t \implies \frac{dy}{dt} = t^{2} - 3$ $\frac{dy}{dx} = \frac{t^{2} - 3}{2 + t}$ $\frac{d}{dt}\left(\frac{dy}{dx}\right) = \frac{2t(2 + t) - (t^{2} - 3)}{(2 + t)^{2}} = \frac{t^{2} + 4t + 3}{(2 + t)^{2}}$ $\frac{d^{2}y}{dx^{2}} = \frac{t^{2} + 4t + 3}{(2 + t)^{2}} \times \frac{1}{2 + t} = \frac{t^{2} + 4t + 3}{(2 + t)^{3}}$	1 1 1 1	
	Stationary points when $\frac{dy}{dx} = 0$, i.e. $t^2 - 3 = 0 \Rightarrow t = \pm\sqrt{3}$ When $t = \sqrt{3}$, $\frac{d^2y}{dx^2} = \frac{3 + 4\sqrt{3} + 3}{(2 + \sqrt{3})^3} > 0$ which gives a minimum. When $t = -\sqrt{3}$, $\frac{d^2y}{dx^2} = \frac{3 - 4\sqrt{3} + 3}{(2 - \sqrt{3})^3} < 0$ which gives a maximum.	1 1 1	no marks for using a nature table no marks for using a nature table
	At a point of inflexion, $\frac{d^2y}{dx^2} = 0$. In this case, that means $t^2 + 4t + 3 = (t + 1)(t + 3) = 0$ and this has exactly two roots. <i>Note that this is a slimmed-down version of</i> <i>the complete story of points of inflexion.</i>	1	need to show 2 values exist

14. (5, 1,3)	(a) $\begin{vmatrix} 4 & 0 & 6 & & 1 \\ 2 & -2 & 4 & & -1 \\ -1 & 1 & \lambda & & 2 \end{vmatrix}$	1	for augmented matrix
	$\begin{vmatrix} 4 & 0 & 6 & & 1 \\ 0 & 4 & -2 & & 3 \\ 0 & 4 & 6 + 4\lambda & & 9 \end{vmatrix}$	1	
	$\begin{vmatrix} 4 & 0 & 6 & 1 \\ 0 & 4 & -2 & 3 \\ 0 & 0 & 8 + 4\lambda & 6 \end{vmatrix}$	1	triangular form needed
	$z = \frac{6}{8+4\lambda} = \frac{3}{2(2+\lambda)}$ $\frac{18+6\lambda}{18+6\lambda}$	1	first root
	$4y = 3 + 2z \implies 4y = \frac{18 + 6\lambda}{4 + 2\lambda}$ $\implies y = \frac{3\lambda + 9}{4(2 + \lambda)}$		
	$4x = 1 - 6z \implies 4x = \frac{2\lambda - 14}{4 + 2\lambda}$ $\implies x = \frac{\lambda - 7}{4(2 + \lambda)}$	1	other two roots
	(b) When $\lambda = -2$, the final row gives $0 = 6$ which is inconsistent. There are no solutions .	1	
	(c) $\lambda = -2.1$; $x = 22.75$; $y = -6.75$; $z = -15$	1,1	1 for first 2 values; 1 for third
	Although the values of λ are close, the values of x, y and z are quite different. The system is ill-conditioned near $\lambda = -2$.	1	

15.
(a)
$$\frac{1}{(x-1)(x+2)^2} = \frac{A}{x-1} + \frac{B}{x+2} + \frac{C}{(x+2)^2}$$
 IM

$$1 = A(x+2)^2 + B(x-1)(x+2) + C(x-1)$$

$$x = 1 \Rightarrow A = \frac{1}{9}$$
1

$$x = -2 \Rightarrow C = -\frac{1}{3}$$
1

$$x = 0 \Rightarrow 1 = \frac{4}{9} - 2B + \frac{1}{3} \Rightarrow B = -\frac{1}{9}$$
1

$$\therefore \frac{1}{(x-1)(x+2)^2} = \frac{1}{9} \left(\frac{1}{x-1} - \frac{1}{x+2} - \frac{3}{(x+2)^2}\right)$$
(b)
$$(x-1)\frac{dy}{dx} - y = \frac{x-1}{(x+2)^2}$$
 IM
(c)
$$(x-1)\frac{dy}{dx} - y = \frac{x-1}{(x+2)^2}$$
 IM
Integrating factor: $\exp\left(1 - \frac{1}{x-1}dx\right)$
1

$$= \exp\left(-\ln(x-1) = (x-1)^{-1}$$
1

$$\frac{1}{(x-1)}\frac{dy}{dx} - \frac{1}{(x-1)^2}y = \frac{1}{(x-1)(x+2)^2}$$
1

$$\frac{d}{dx} \left(\frac{y}{x-1}\right) = \frac{1}{(x-1)(x+2)^2}$$
1

$$\frac{1}{9} \left(\frac{1}{x-1} - \frac{1}{x+2} - \frac{3}{(x+2)^2}\right)$$
1

$$\frac{y}{x-1} = \frac{1}{9} \left(\ln|x-1| - \ln|x+2| + \frac{3}{x+2}\right) + c$$
1

$$y = \frac{x-1}{9} \left(\ln|x-1| - \ln|x+2| + \frac{3}{x+2}\right) + c(x-1)$$
(c) stant of integration needed.

16. (6,4)	(a) For $n = 1$, the LHS = $\cos \theta + i \sin \theta$ and the RHS = $\cos \theta + i \sin \theta$. Hence the result is true for $n = 1$.	1	
	Assume the result is true for $n = k$, i.e. $(\cos \theta + i \sin \theta)^k = \cos k\theta + i \sin k\theta$.	1	working with <i>n</i> is penalised.
	Now consider the case when $n = k + 1$: $(\cos\theta + i\sin\theta)^{k+1} = (\cos\theta + i\sin\theta)^k (\cos\theta + i\sin\theta)$ $= (\cos k\theta + i\sin k\theta) (\cos\theta + i\sin\theta)$ $= (\cos k\theta \cos\theta - \sin k\theta \sin\theta) + i (\sin k\theta \cos\theta + \cos k\theta \sin\theta)$ $= \cos (k + 1)\theta + i\sin (k + 1)\theta$ Thus, if the result is true for $n = k$ the result is true for $n = k + 1$. Since it is true for $n = 1$, the result	1 1 1	for applying the inductive hypothesis multiplying and collecting
	is true for all $n \ge 1$.	1	
	(b) $\frac{\left(\cos\frac{\pi}{18} + i\sin\frac{\pi}{18}\right)^{11}}{\left(\cos\frac{\pi}{36} + i\sin\frac{\pi}{36}\right)^4} = \frac{\cos\frac{11\pi}{18} + i\sin\frac{11\pi}{18}}{\cos\frac{\pi}{9} + i\sin\frac{\pi}{9}}$ $= \frac{\cos\frac{11\pi}{18} + i\sin\frac{11\pi}{18}}{\cos\frac{\pi}{9} + i\sin\frac{\pi}{9}} \times \frac{\cos\frac{\pi}{9} - i\sin\frac{\pi}{9}}{\cos\frac{\pi}{9} - i\sin\frac{\pi}{9}}$ $= \frac{\cos\frac{11\pi}{18}\cos\frac{\pi}{9} + \sin\frac{11\pi}{18}\sin\frac{\pi}{9}}{\cos^2\frac{\pi}{9} + \sin^2\frac{\pi}{9}} + \text{imaginary term}$ $= \cos\left(\frac{11\pi}{18} - \frac{\pi}{9}\right) + \text{imaginary term}$ $= \cos\frac{\pi}{2} + \text{imaginary term}$	1 1 1	using result from above
	Thus the real part is zero as required.	1	or equivalent

END OF SOLUTIONS